

Wavefront Sensing and Control



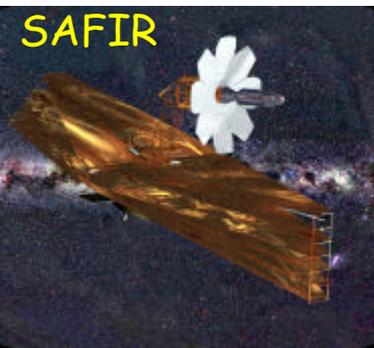
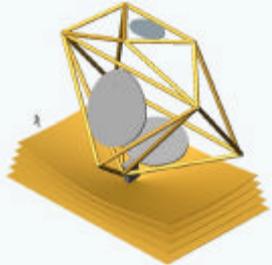
David van Buren
Jet Propulsion Laboratory



Large Space Telescopes Need WFS&C

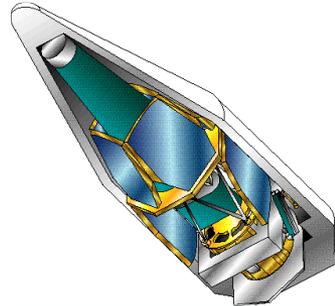
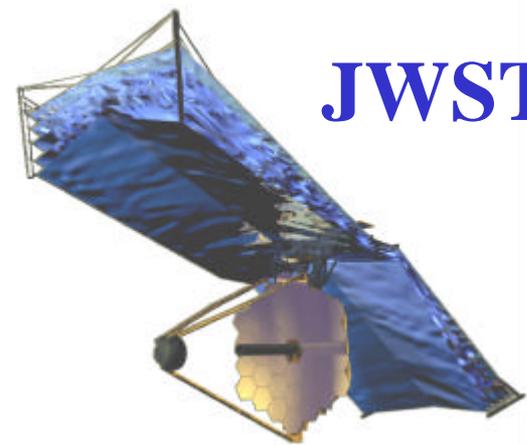
Mission	Aperture (m)	Wavelength	WFS&C WFE	Total WFE	Dynamic range	Spatial resolution	Bandwidth	Tech Freeze date
HST	2.4	UV-IR						
FUSE	0.37	UV						
SIRTF	0.85	IR						
GALEX	0.5	UV						
Kepler	0.95	VIS						
JWST	6 to 7	IR	10 nm	150 nm	1.00E+06	5 cyc/ap	1.00E-06	2004
Coronagraph precursor	1 to 3	VIS	50 pm	100 pm in band	1.00E+05	30+cyc/ap	1.00E-05	2005?
SIM	0.5	VIS						
TPF Coronagraph	8 to 10	VIS	40 pm	50 pm in band	1.00E+06	30+cyc/ap	1e-3 to 1e-6	2008?
TPF IFO	3 to 4	IR	1 nm	10 nm		5-10 cyc/ap		2008?
SAFIR	8 to 10	FIR/SubMM	100 nm?	1 um?	1.00E+05			2011?
Large UV/Opt	big	UV-VIS	1 nm	10 nm	1.00E+06	high	low	2016?
Life Finder	15+	undefined	undefined	undefined	undefined	undefined	undefined	2016?

- Future NASA missions promise to open new frontiers in astronomy using large aperture space telescopes
- Getting large apertures into space requires segmenting or folding the primary optic to fit in a booster shroud
- Wavefront control after deployment is required to achieve high optical quality
- JWST mission is pioneering space telescope WFS&C





JWST WF Sensing and Control



- Primary mirror will be deployed, with from 18 to 36 segments
- Telescope will be cooled to cryo temperatures
- Initial misalignments and figure errors may be large!!!
- **WFS&C's job is to align telescope and correct figure errors to achieve diffraction-limited imaging at 2 um wavelength**
- We do this with actuators that move and deform the segments
- WF sensing data is provided by science camera images and spectra, which are processed on the ground to determine actuator commands
- JWST will be very stable, by virtue of its environment and design
- Actuators will be off during observations
- Periodic WFS&C updates will keep performance in spec



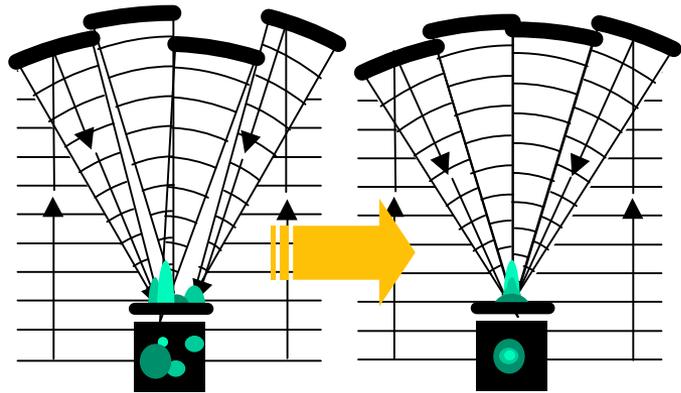
WFS&C Modes

	NGST Performance Expected		Demonstrated in the Lab	
Control Mode	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)
Coarse Alignment	5 mm	10 μ m	5 mm	10 μ m
Coarse Phasing	50 μ m	1 μ m	50 μ m	100 nm
Fine Phasing	5 μ m	<100 nm	3 μ m	20 nm
Actuator Calibration		<10 nm	2 nm	2 nm
Camera-specific WFE Calibration		<10 nm	<10 nm	3.5 nm
PSF Monitoring		<10 nm sensing		6 nm sensing

- The baseline JWST WFC has 3 main initialization modes: Coarse Alignment; Coarse Phasing and Fine Phasing
- Each mode reduces the error it starts with by many times, and then hands over to the succeeding mode
- PSF Monitoring monitors science observations to track the evolving WF error over long periods of time
- Fine Phasing is repeated at intervals (1/month?) throughout the mission



Coarse Alignment - Capture and Tilt



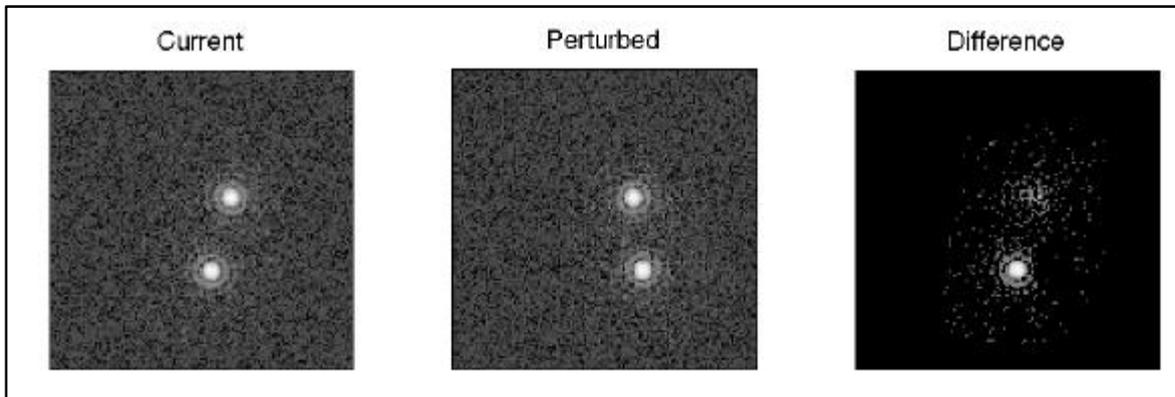
Government Baseline		NGST Performance		Demonstrated in the Lab	
Control Mode	Algorithm	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)
Coarse Alignment	Segment ID	5 mm		5 mm	
	Coarse Align				
	Focus		10 um		10 um

- At first light, the telescope is pointed at a bright, isolated star
- The initial image is broken into many blobs: defocussed, separated segment images
- Segment ID takes an image, moves segments incrementally, takes another image, then "differentiates" the 2 images to identify which blob corresponds to which segment
- Missing spots trigger a larger segment scan, stepping segment tilts in units of the camera field of view, until that segment is found
- Once identified, segment spots are placed in particular positions on the detector for Focus

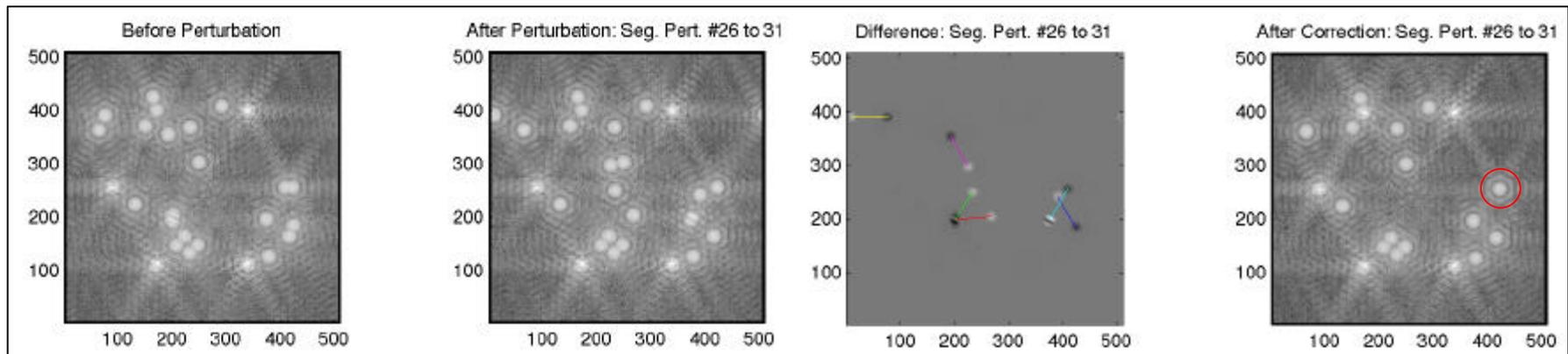


Coarse Align Image Differentiation Examples

- Small tilts Dx_i and Dy_i are introduced between exposures (here i is the i th segment)
- The difference frame is $DI_i = pos/I_i(x_i, y_i) - I_i(x_i + Dx_i, y_i + Dy_i)/$



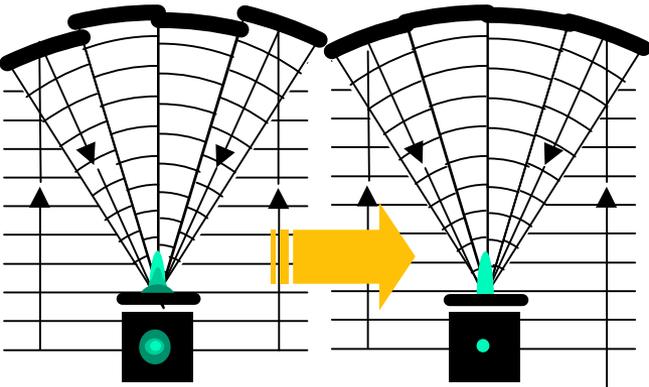
Example from WCT-2 testbed. Difference shows the location of the segment blob.



Example using JWST simulation with large number of segments. 6 segments are identified simultaneously, and moved to overlie at the reference location.

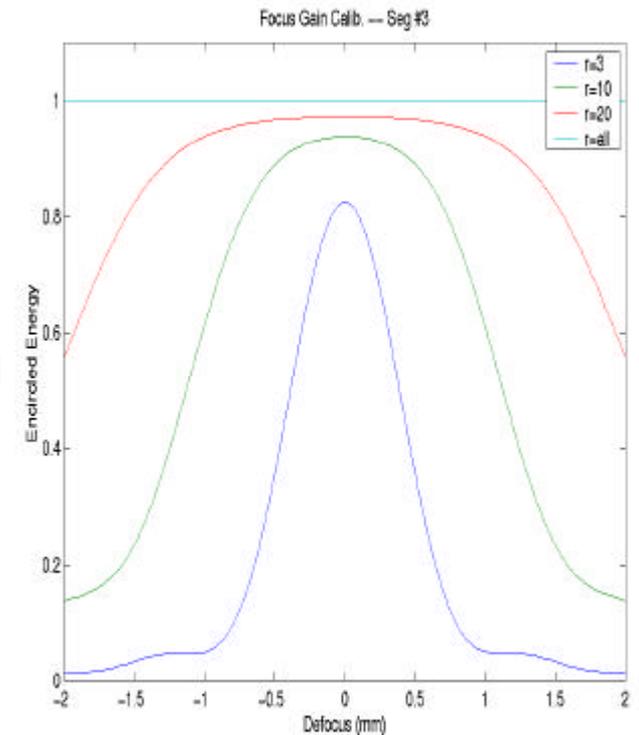


Coarse Alignment - Focus



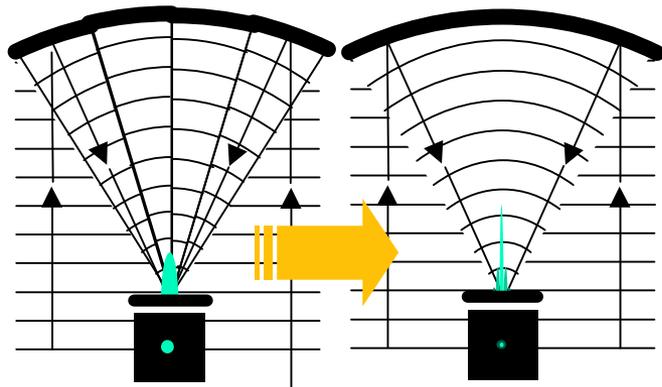
Government Baseline		NGST Performance		Demonstrated in the Lab	
Control Mode	Algorithm	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)
Coarse Alignment	Segment ID	5 mm		5 mm	
	Coarse Align				
	Focus		10 μm		10 μm

- Each segment is focused by driving it in piston to minimize a 3-stage encircled-energy metric
- When defocus is large, steps are computed using geometric optics, and convergence is rapid
- When near the segment depth of focus, a hill-climbing method is used
- When completed, segments are focused but not coherently phased
 - Piston errors in the 10s of microns



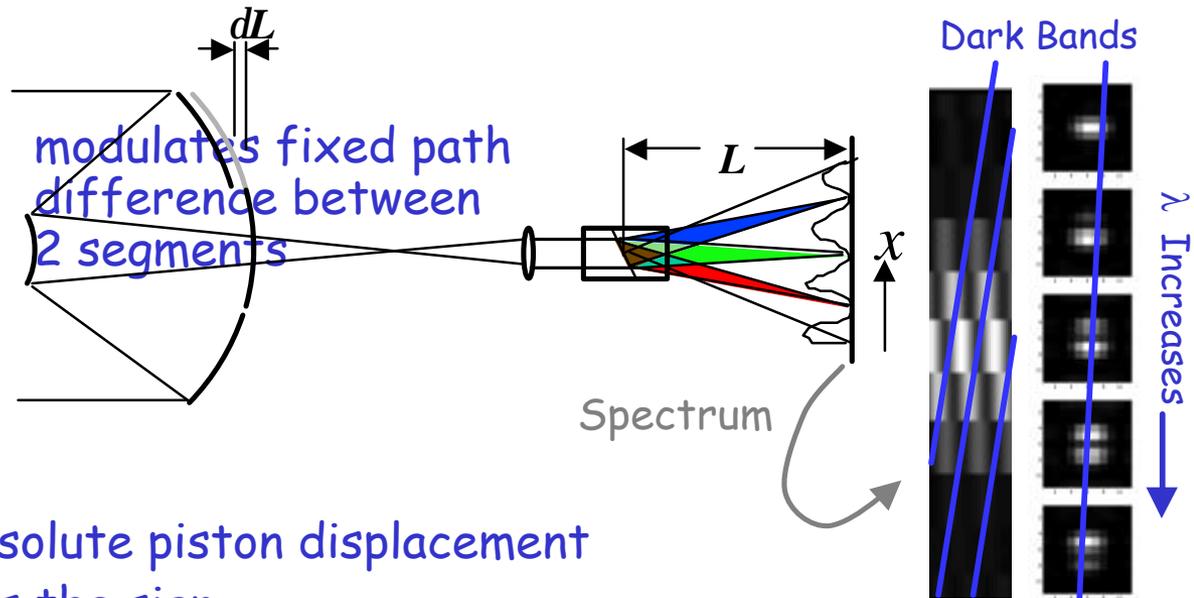


Coarse Phasing - DFS



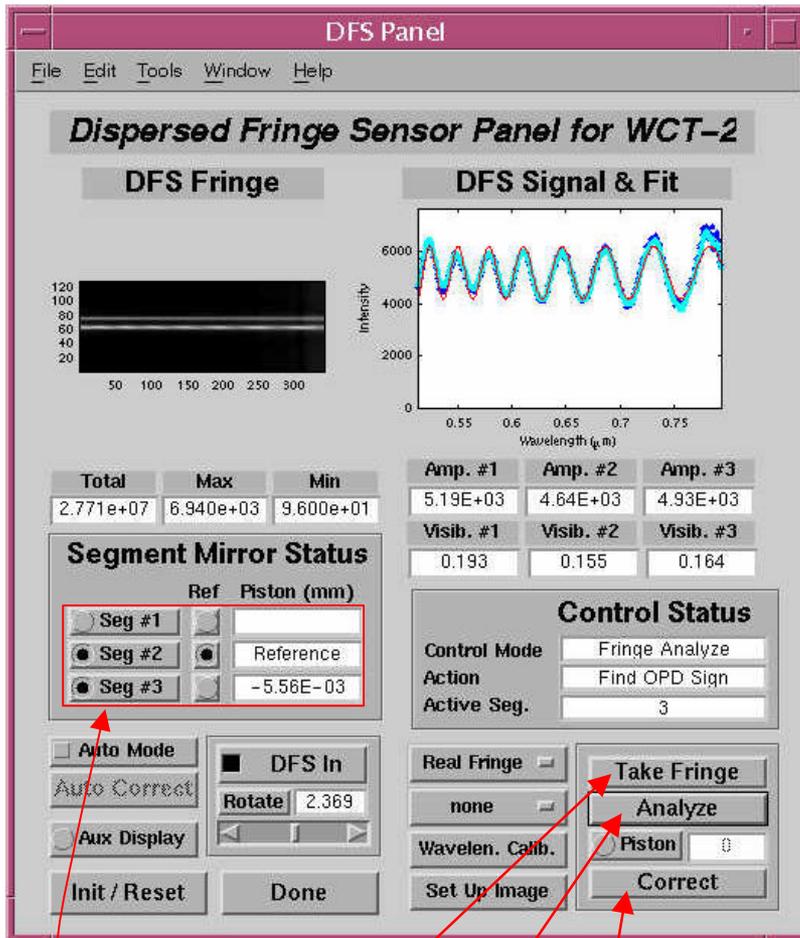
Government Baseline		NGST Performance		Demonstrated in the Lab	
Control Mode	Algorithm	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)
Coarse Phasing	Dispersed-Fringe Sensing	50 μm	1 μm piston error	50 μm	100 nm piston error
	White-Light Interferometry	10 μm	10 nm piston error	5 μm	20 nm piston error

- Wavelength variation
- Bright where λ is coherent with dL
- Null where it combines destructively
- Period of fringe gives absolute piston displacement
- Slope of dark bands gives the sign

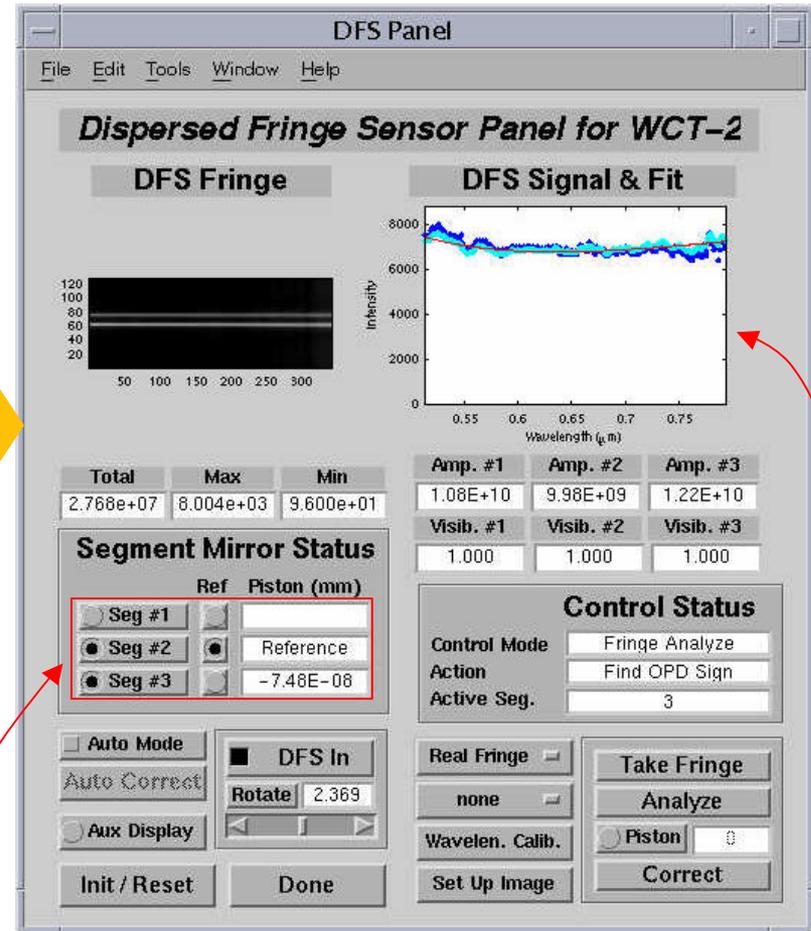




Coarse Phasing - DFS Example from WCT-2



1. Take picture
2. Analyze picture to extract fringe
3. Result
4. Implement correction

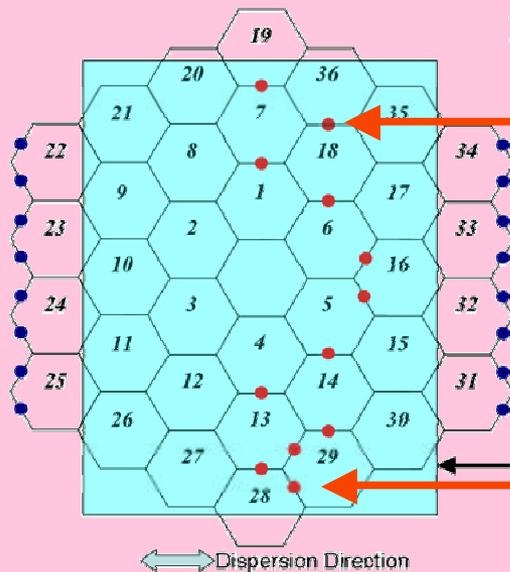
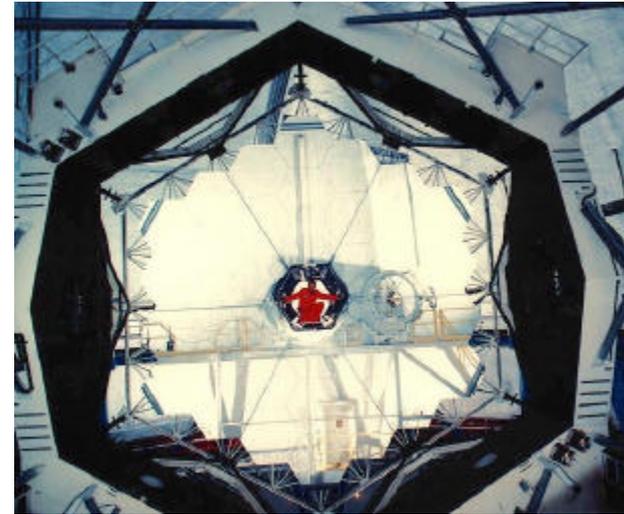


- Post-correction fringe shows very little modulation
- Detected piston reduced to near zero



DFS at Keck

- Dispersed Fringe Sensing demonstrated using Keck 2
 - JWST shares Keck Aperture: 36 hexagonal segments
 - DFS piston measurements obtained using a combined DFS + Shack-Hartmann mask covering a subset of edges.
 - DFS results should match piston commands
 - DFS results should also match Keck "Phasing Camera System" (PCS) measurements
 - ◆ PCS is, a modified Shack-Hartmann sensor that uses WLI to find edge offsets
- DFS Performance summary (preliminary):
 - Capture range: >30 mm
 - Accuracy: <300 nm

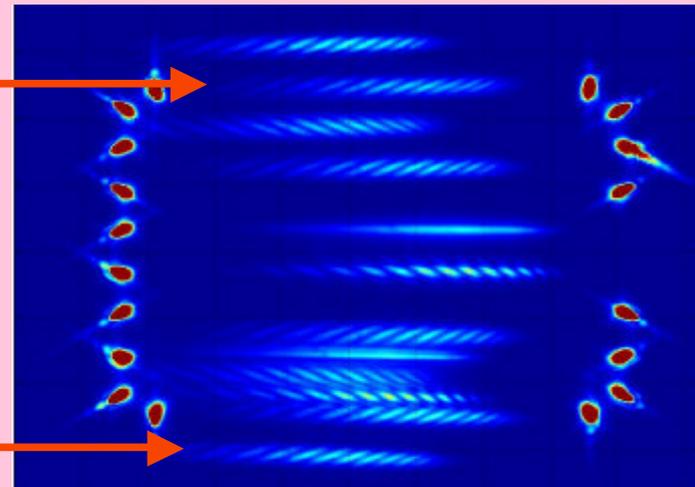


Edge-Sampled Spots in DFS Experiment

Spot selection gives:

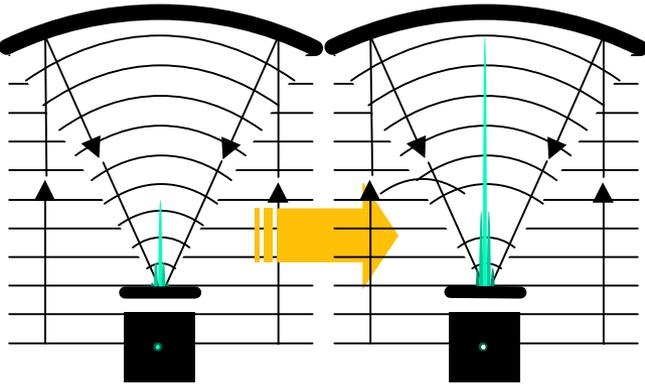
- Orientations
- Separations
- Registration

- Edges measured with DFS
- Peripheral spots for pupil registration





Fine Phasing - WF Sensing



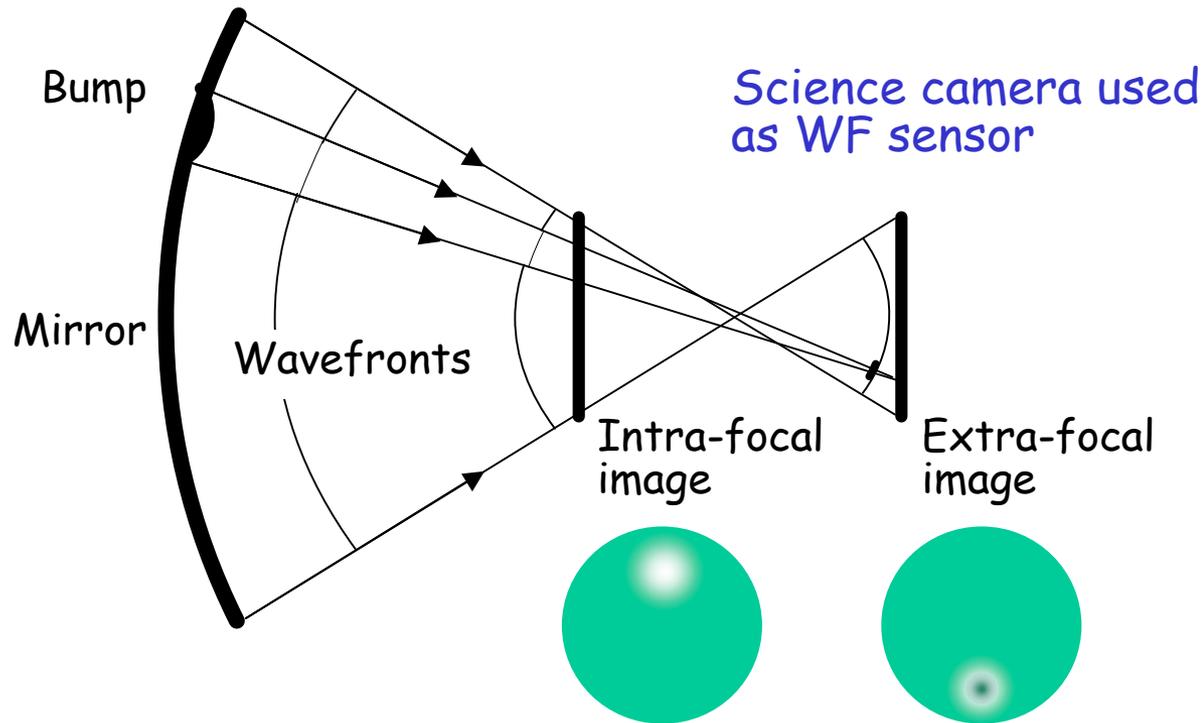
Government Baseline		NGST Performance		Demonstrated in the Lab	
Control Mode	Algorithm	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)
Fine Phasing	WFS/MGS	>15 μm	<10 nm	>3 μm	3.5 nm
	WFC	>15 μm	<100 nm	>3 μm	20 nm

- Image-based WF sensing has important advantages...

Method	Instrument	Common mode reject	Accuracy	Range	Spatial resolution	Noise & jitter	Resolves piston?
Image-based	Any camera, any field	Yes	Excellent	Med (50 μm)	High	Robust	Yes (multi-color)
Hartman sensor	Dedicated or flip-in	No	Good	High (1 mm)	Med	Robust	No
Shearing interf.	Dedicated	No	Good	Med	High	Robust	Maybe
Phase-shifting interf.	Dedicated	No	Excellent	Med	High	Sensitive	Yes (multi-color)



WF Sensing Using Defocussed Images

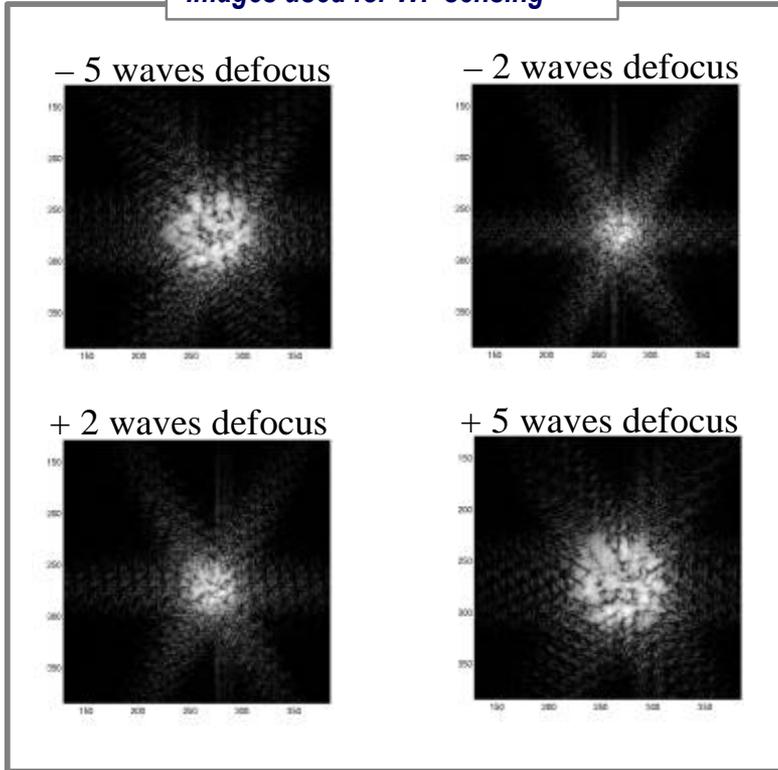


- Bumps on a mirror surface shift the focus of patches of the beam
- These show up as bright spots on one side of focus and dark spots on the other
- The pupil and defocussed images are related by Fourier transforms
- Iterative processing of multiple defocussed images correlates the intensity variations in each, derives common WF phase map

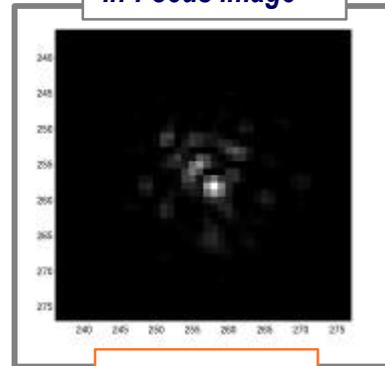


Fine-Phasing JWST in Simulation

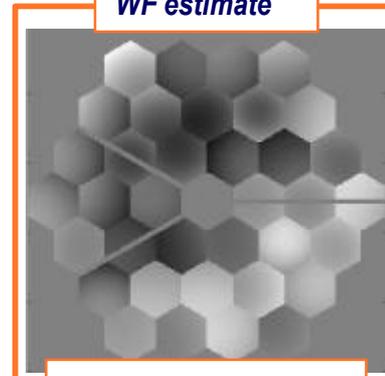
Images used for WF sensing



In-Focus image



WF estimate

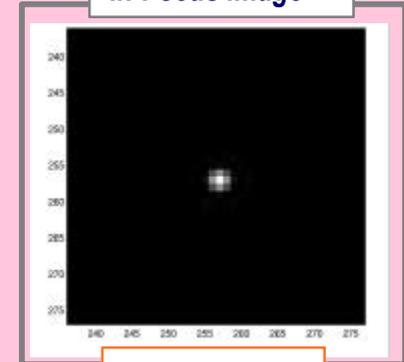


WFE=480 nm RMS

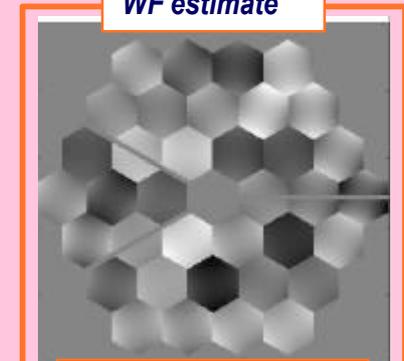
- Fine Phasing uses MGS Phase Retrieval to estimate WF
- WF control is applied using segment RB and RoC actuators

- Post-control WF meets 150 nm objective

In-Focus image



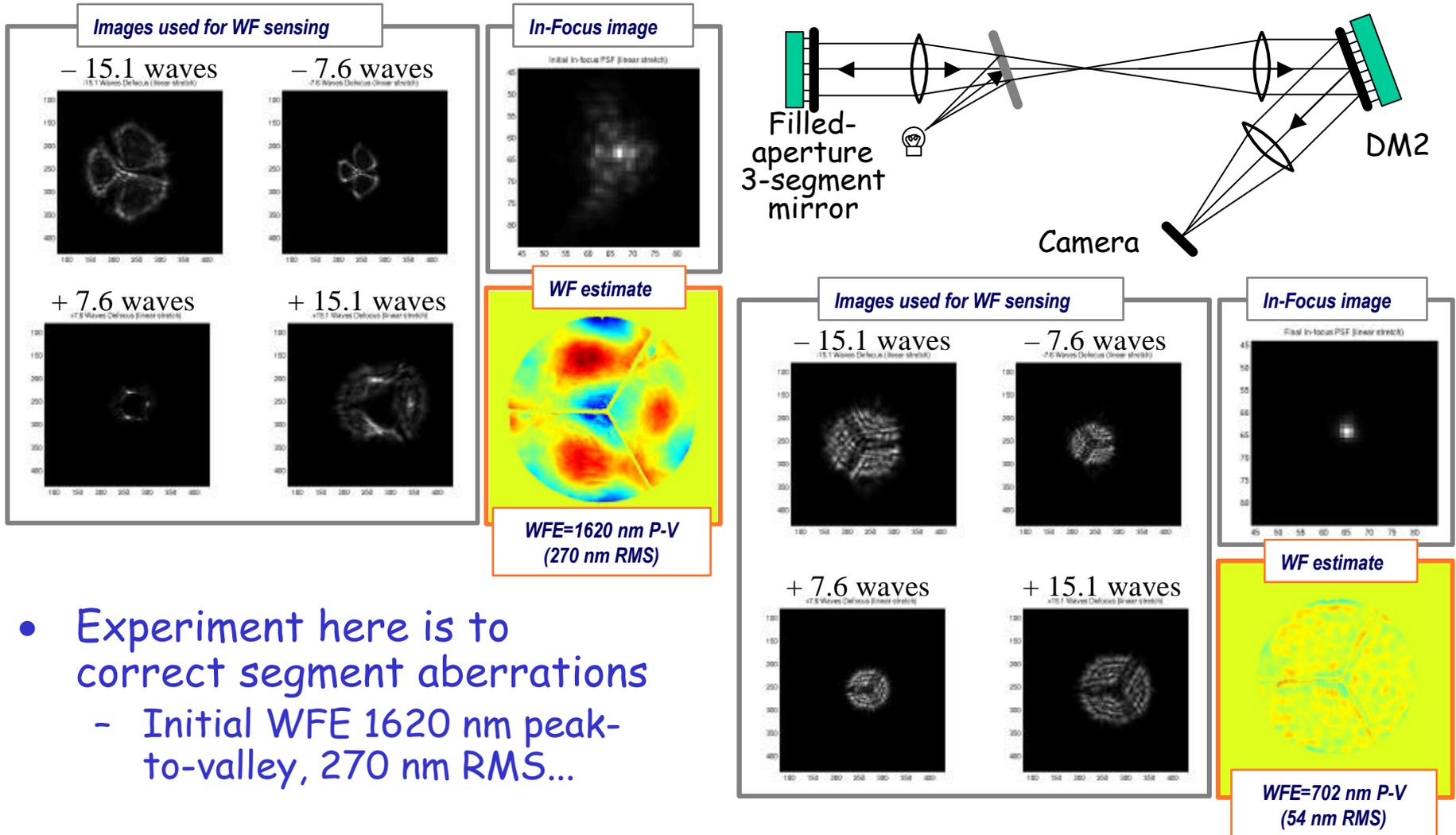
WF estimate



WFE= 35 nm RMS



Example from WCT-3

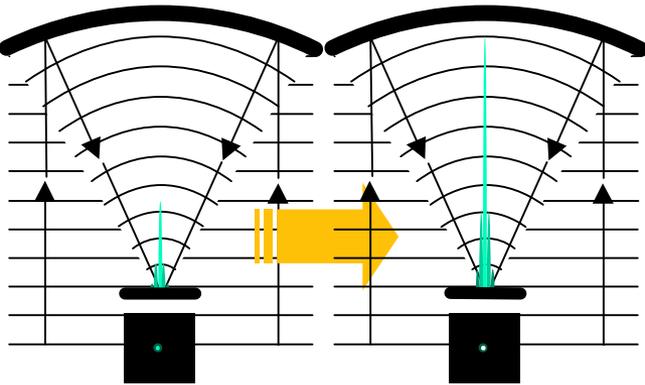


- Experiment here is to correct segment aberrations
 - Initial WFE 1620 nm peak-to-valley, 270 nm RMS...

- After DM and segment control ...reduced to 54 nm RMS

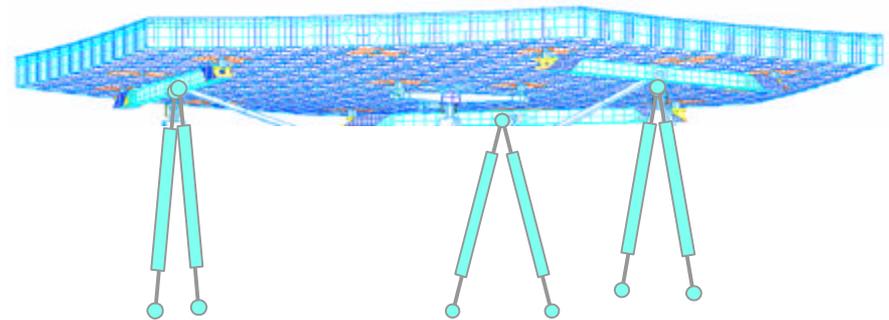


Fine Phasing - WF Control



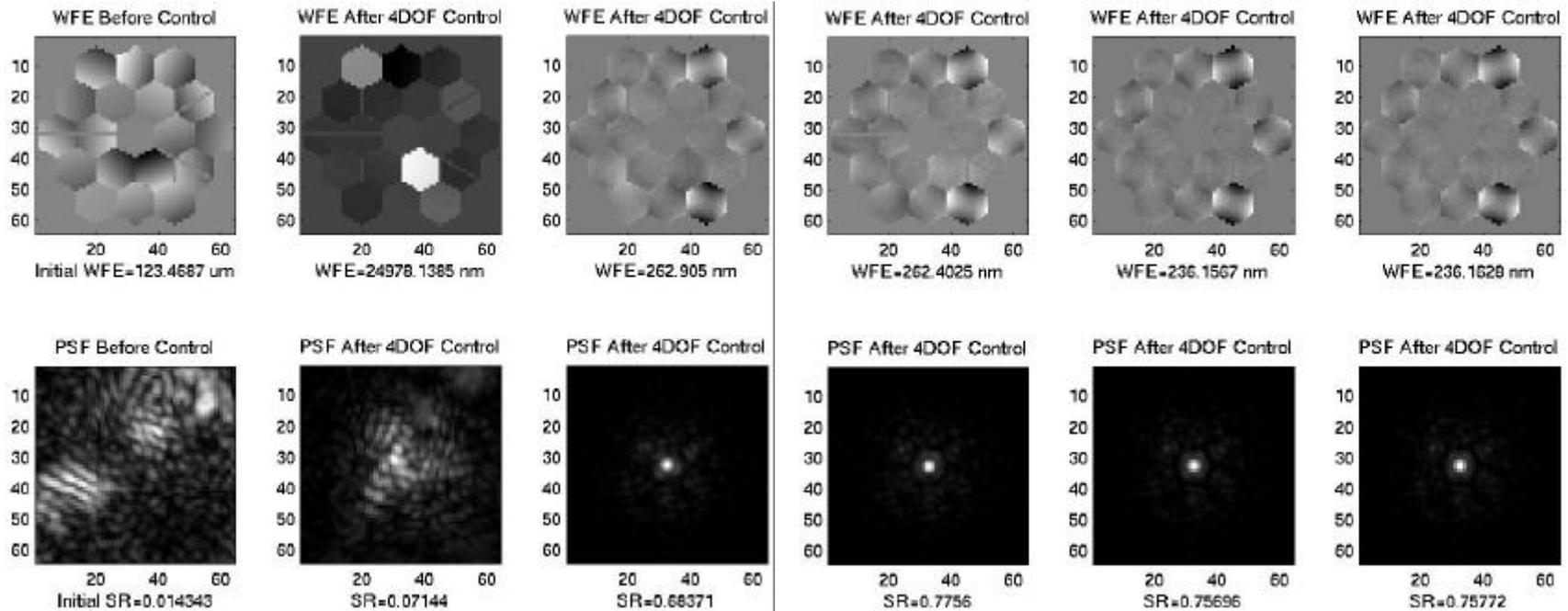
Government Baseline		NGST Performance		Demonstrated in the Lab	
Control Mode	Algorithm	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)
Fine Phasing	WFS/MGS	>15 μm	<10 nm	>3 μm	3.5 nm
	WFC	>15 μm	<100 nm	>3 μm	20 nm

- WF control is effected using actuators to move segments in 6DOF and to change segment RoC
- 2-stage linear actuators grouped into 3 bipods move segments in tip, tilt, twist, decenter (X and Y) and piston
 - Coarse stage provides long stroke, looser accuracy
 - Fine stage provides short stroke, finer precision





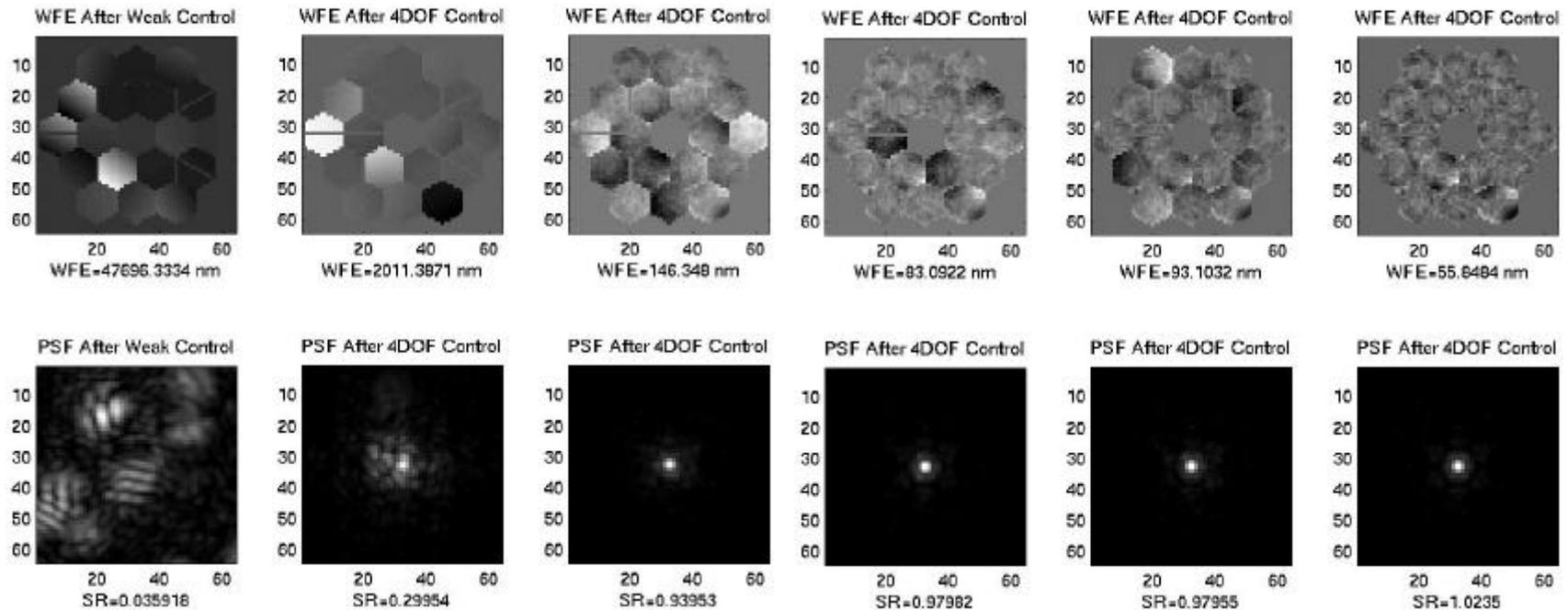
WF Control with Hexapods Example



- Fine Phasing (WFS and WFC) initiated with large errors in all rigid-body and RoC DOFs
- Stroke-dependent actuation error
 - Large actuator stroke leaves large actuation error
 - Subsequent smaller actuator commands leave less actuation error
 - 3-4 iterations are necessary to reduce actuator error to smallest level, corresponding to minimum error (3 nm)



Example (cont.)

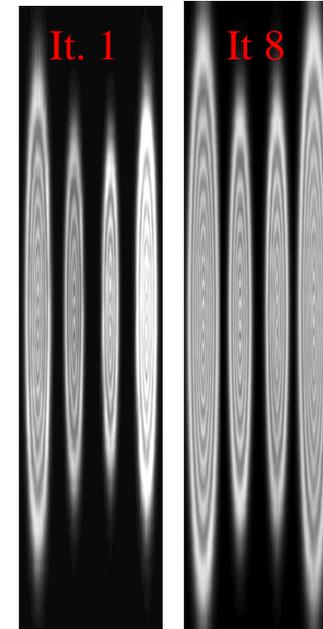


- “Weak” DOFs (decenter and twist) are controlled
 - Weak influence of these DOFs means large motions are necessary to compensate small aberrations
 - Large actuator movements leave large actuation errors in 4 strong DOFs
- A 2nd round of 4DOF control cleans up actuation errors and control nonlinearities

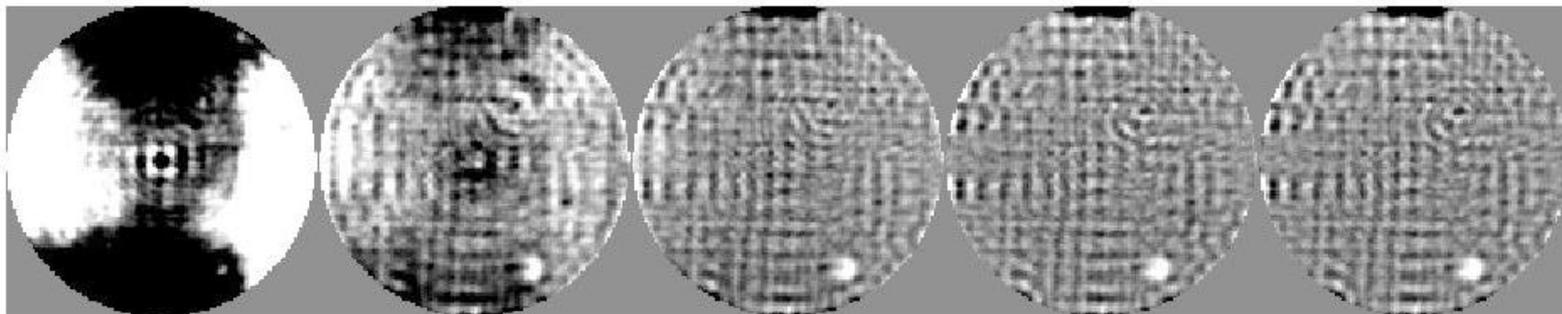


High Contrast Imaging Testbed

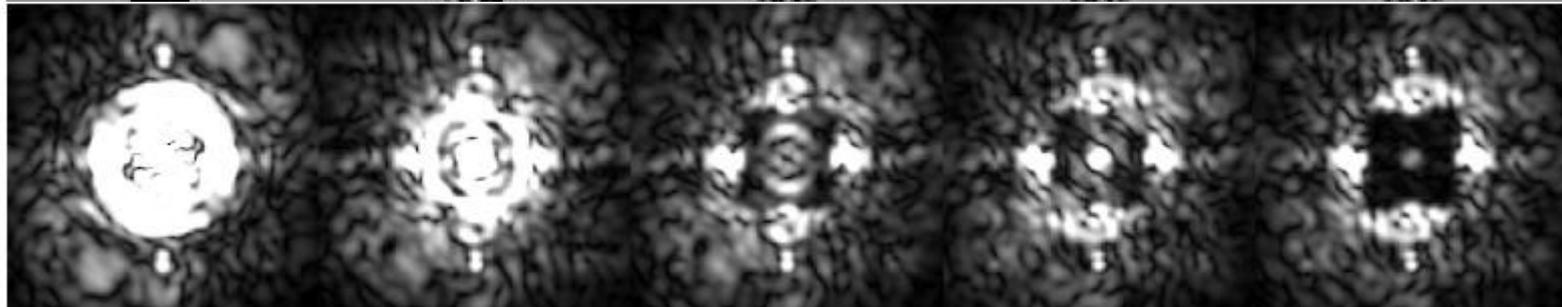
- The TPF HCIT is intended to demonstrate extremely high contrast coronagraphy for planet hunting
- Requires suppressing scattered light in low and mid spatial frequencies using (in this example) a 32^2 actuator DM
- This chart shows a sequence of WFS&C iterations leading to a WF corrected to $\lambda/5000$ for spatial frequencies within the DM bandpass



Sequence of
Wavefront
Estimates

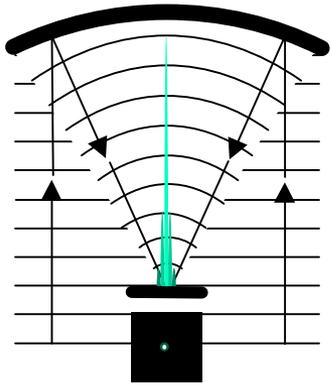


Sequence of
WFE Power
Spectral
Densities

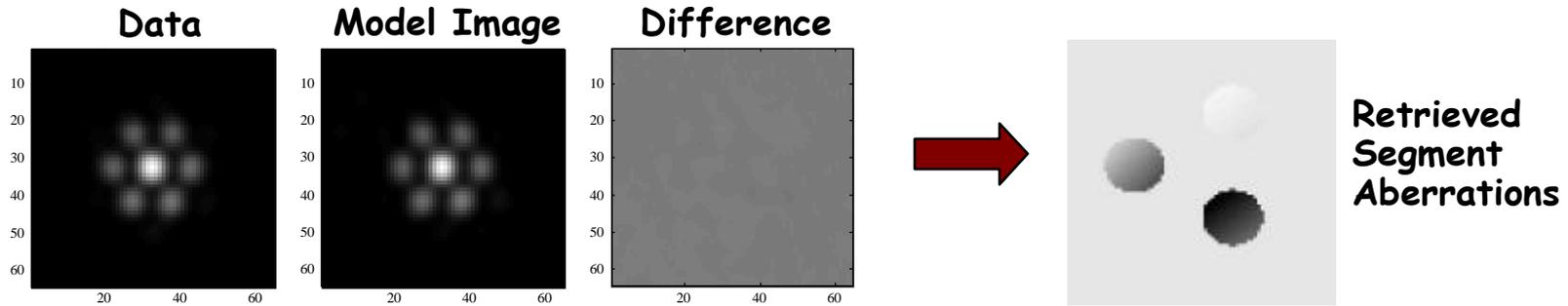




PSF Monitoring



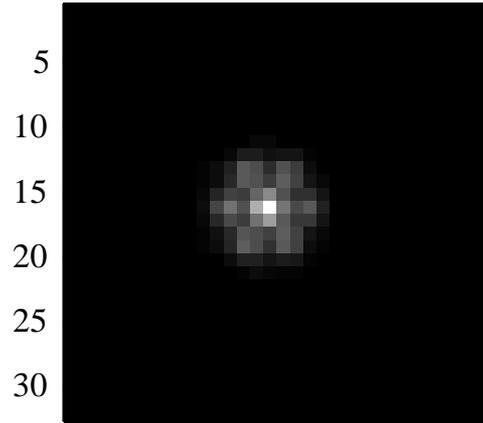
Government Baseline		NGST Performance		Demonstrated in the Lab	
Control Mode	Algorithm	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)	Capture Range (peak-valley WFE)	Accuracy (rms WFE or WFSE)
PSF Monitoring	IPO/ Prescription Retrieval		<10 nm		6 nm
Fine Phasing	WFS/MGS	>15 um	<10 nm	3 um	3.5 nm
	WFC	>15 um	<100 nm	3 um	20 nm



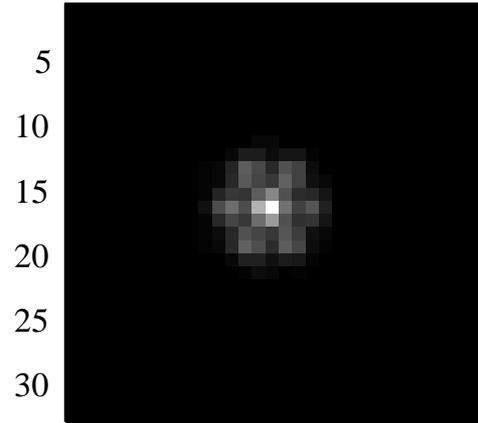
- In-focus PSF Optimizer (IPO) measures low spatial- f components of WFE from narrow-band in-focus images
 - IPO uses Prescription Retrieval model-matching algorithm
- IPO provides robust, accurate control for WCT-2
- IPO images can be taken from the science data stream: a near-zero overhead means of monitoring the evolving WFE

PSF Monitoring Example from WCT-2

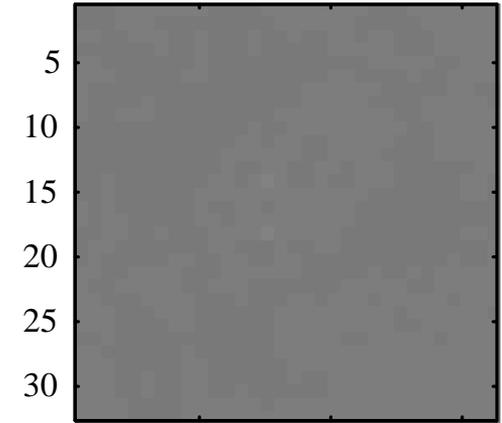
Data Image



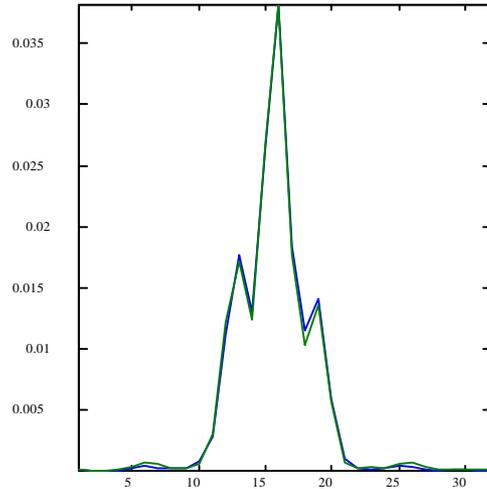
Model Image



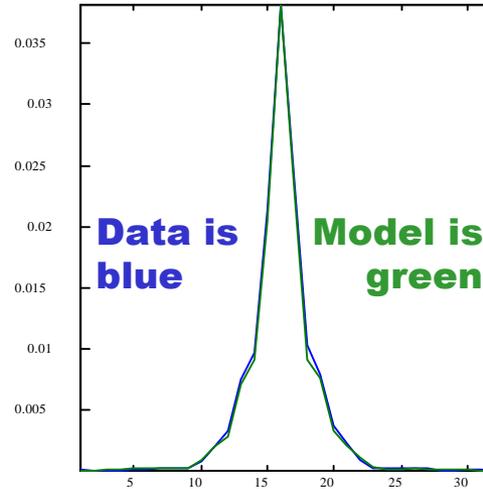
Difference



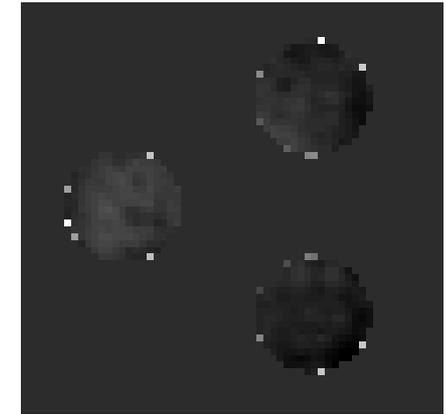
Horizontal Slice



Vertical Slice



10 20 30



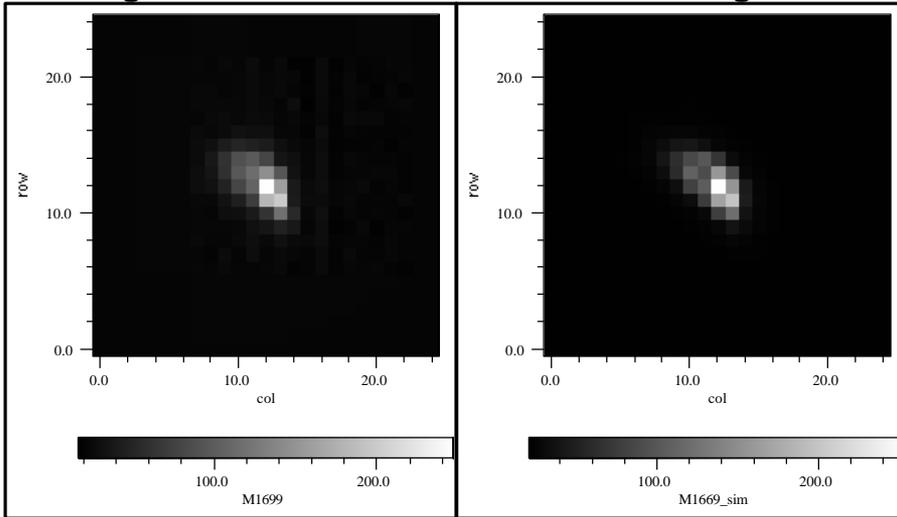
- WCT-2 data
 - 900 nm filter
 - 0.1 sec exposure time

- No PSF magnifier
- Match = 0.026 RSS vs. total of 25



Mars Observer Camera Example

Image M1699: Actual and Simulated Images



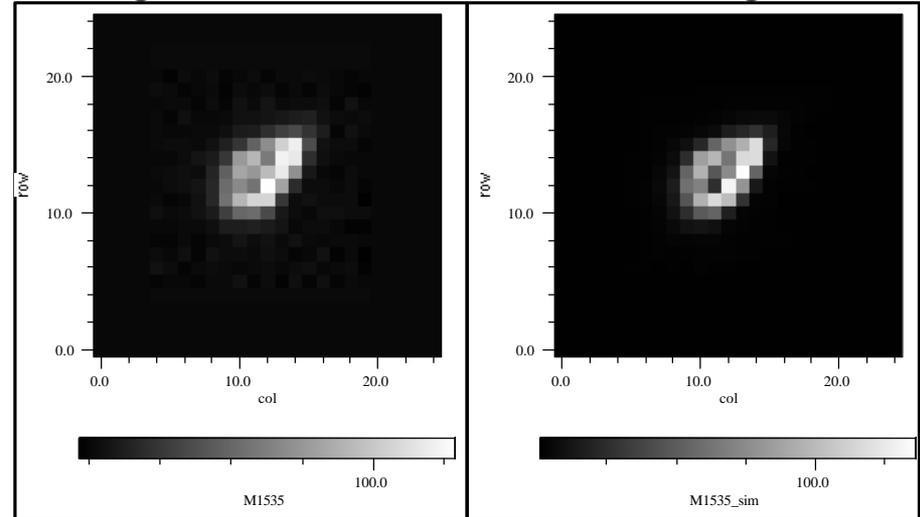
Actual image

Simulated image

G Image-specific parameter results

È Focus: 1 Watt hub heater yields 0.1814 μm	È Intensity: 2.961 (unitless)
È Field: 0.4485 mrad	È Background: 20.828 (DN)

Image M1535: Actual and Simulated Images



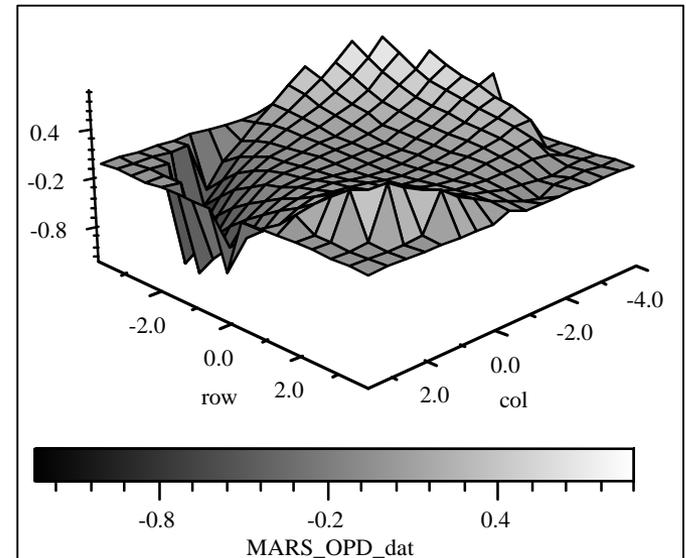
Actual image

Simulated image

G Image-specific parameter results

È Focus: 3 Watt rim heater yields -0.2908 μm	È Intensity: 2.8958 (unitless)
È Field: 1.806 mrad	È Background: 20.498 (DN)

- Diagnostic data taken en route to Mars
- Illustrates prescription retrieval with low resolution, low SNR, broadband data





WF Sensing and Control Is Built On...

- *Good computational models*
 - Embedded in WFS and WFC algorithms
 - Simulations for development before the hardware is ready
- *Good analysis*
- *Good devices*
- *Good experiments*
- *OK optics!*



Conclusion

- The JWST Government WFS&C Team has developed a complete WFS&C system that is capable of meeting mission requirements
- This system has been tested to TRL 4
- We are now working closely with TRW/Ball (the new JWST Prime Contractor), who have the ultimate responsibility for JWST
- JWST WFS&C will be at TRL 6 by the NGST Non-Advocate Review (2004?)